

Properties of linear regression model estimators

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- The linear regression model is one of the form:

$$Y_i = \beta_0 + \beta_1 X_{1,i} + \beta_2 X_{2,i} + \dots + \beta_J X_{J,i} + u_i$$

- Or, $Y = X\beta + U$
where $\beta = (\beta_0, \beta_1, \beta_2, \dots, \beta_J)'$
- The linear regression model estimates are those which minimise the sum of squared errors:

$$\begin{aligned} \sum \epsilon_i &= \sum (Y_i - \beta_0 - \dots - \beta_J X_{J,i}) = 0 \\ \min_{\beta, \sigma^2} \sum (Y_i - \beta_0 - \beta_1 X_{1,i} - \dots - \beta_J X_{J,i})^2 &= \min_{\beta, \sigma^2} \sum u_i^2 \end{aligned}$$

- Jargon: The model is referred to as the “Data Generating Process” (DGP).

- For a simple one-exogenous variable model,

$$Y_i = \beta_0 + \beta_1 X_{1,i} + u_i$$

- β_0 is the intercept on the “regression line” and β_1 is the slope.
- The above equation is called the “population regression line”.
- After estimation, we have $Y_i = \hat{\beta}_0 + \hat{\beta}_1 X_{1,i} + u_i$ which is called the “estimated/sample regression line”
- $\hat{\beta}_0 = \bar{Y} - \hat{\beta}_1 \bar{X}$
the “regression line” passes through the mean of the dataset.
- $\hat{\beta}_1 = S_{xy} / S_{xx}$
where S_{xy} is the sample covariance and S_{xx} is the sample variance of the exogenous data X .

Properties of linear regression estimators

Questions after the regression

- $(\hat{\beta}_0, \hat{\beta}_1)$ are the estimated parameters that provide the “best fit” to the data.
- But we also ask other questions:
 - 1 What are their sample statistical properties?
 - 2 What reliability/ precision they have?
 - 3 How can we use the estimates to test a hypothesis?
 - 4 How can we use the estimates when forecasting the Y_i ?
- These are questions about how a sample estimate can be used to capture knowledge about the population estimate.

Sample properties of regression estimators

- Sample statistical features will be the distribution of the estimator.
- This distribution will have a mean and a variance, which in turn, leads to the following properties of estimators:
 - 1 Unbiasedness: $E(\hat{\beta}) = \beta$
 - 2 Consistency: As $N \rightarrow \infty$, $\hat{\beta} = \beta$, $var(\hat{\beta}) \rightarrow 0$.
 - 3 Efficiency: $E(\hat{\beta})^2$ is minimum among all other estimators

Testing unbiasedness: Mean of (β_0, β_1)

- Each estimated value may differ from β_0, β_1 , but their expected/ average value would be equal to β_0, β_1 .
- Thus, if these estimators are “unbiased”, then

$$E(\hat{\beta}_0) = \beta_0$$

$$E(\hat{\beta}_1) = \beta_1$$

Assumptions needed for unbiasedness of β_0, β_1

- $E(u_i|X_i) = 0$

$$\Rightarrow E(u_i) = 0$$

(by law of iterated expectations)

- X_i 's are fixed and non-stochastic.

$$\Rightarrow Cov(X_i, u_i) = 0$$

- Working this out:

$$\begin{aligned}Cov(X_i, u_i) &= E[(X_i - E(X_i))(u_i - E(u_i))] \\&= E(X_i u_i) - E(X_i)E(u_i) \\&= X_i E(u_i) - E(X_i)E(u_i) \\&= X_i E(u_i) - X_i E(u_i) \\&= 0\end{aligned}$$

Proof that $E(\hat{\beta}_1) = \beta_1$

- $\hat{\beta}_1 = \frac{S_{XY}}{S_{XX}}$
- S_{XY} works out to be:

$$\begin{aligned} &= \sum X_{1,i} Y_i - \frac{1}{N} \sum X_{1,i} \sum Y_i \\ &= \sum X_{1,i} [\beta_0 + \beta_1 X_{1,i} + u_i] - \frac{1}{N} \sum X_i \sum (\beta_0 + \beta_1 X_{1,i} + u_i) \\ &= \beta_0 \sum X_{1,i} + \beta_1 \sum X_{1,i}^2 + \sum X_{1,i} u_i \\ &\quad - \frac{1}{N} \sum X_{1,i} [N\beta_0 + \beta_1 \sum X_{1,i} + \sum u_i] \\ &= \beta_0 \sum X_{1,i} + \beta_1 \sum X_{1,i}^2 + \sum X_{1,i} u_i \\ &\quad - \beta_0 \sum X_{1,i} + \beta_1 \frac{1}{N} [\sum X_{1,i}]^2 - \frac{1}{N} \sum X_{1,i} \sum u_i \\ &= \beta_1 \left[\sum X_{1,i}^2 - \frac{1}{N} [\sum X_{1,i}]^2 \right] + \left[\sum X_{1,i} u_i - \frac{1}{N} \sum X_{1,i} \sum u_i \right] \end{aligned}$$

- So,

$$S_{XY} = \beta_1 S_{XX} + S_{Xu}$$

Proof that $E(\hat{\beta}_1) = \beta_1$

Thus:

$$\begin{aligned}\hat{\beta}_1 &= \frac{S_{XY}}{S_{XX}} \\ &= \frac{\beta S_{XX} + S_{Xu}}{S_{XX}} = \beta \frac{S_{XX}}{S_{XX}} + \frac{S_{Xu}}{S_{XX}} \\ \hat{\beta}_1 = \beta_1 + \frac{S_{Xu}}{S_{XX}} E(\hat{\beta}_1) &= \beta_1 + E\left(\frac{S_{Xu}}{S_{XX}} | X\right) \\ &= \beta_1 + \frac{1}{S_{XX}} \cdot E(S_{Xu} | X) \\ \text{Or, } E(\hat{\beta}_1) &= \beta_1 + \frac{1}{S_{XX}} E(S_{Xu} | X)\end{aligned}$$

Proof that $E(\hat{\beta}_1) = \beta_1$

- Then,

$$\begin{aligned}E(S_{Xu}|X) &= E\left[\sum(X_{1,i} - \bar{X}_1)(u_i - \bar{u})\right] \\&= \sum E(X_{1,i} - \bar{X}_1)(u_i - \bar{u}) \\&= \sum (X_{1,i} - \bar{X}_1)E(u_i - \bar{u}) \\&= 0\end{aligned}$$

Therefore $E(\hat{\beta}_1|X) = \beta_1$ → Unbiased

By law of iterated expectation $E(\hat{\beta}_1) = \beta_1$.

Show that $E(\hat{\beta}_0) = \beta_0$

Property 2: Consistency

- If we have two estimators, $\hat{\beta}_{0,n}, \hat{\beta}_{1,n}$

$$(\hat{\beta}_{0,n=1}, \hat{\beta}_{1,n=1}) \cdots (\hat{\beta}_{0,n=m}, \hat{\beta}_{1,n=m})$$

- As $(n = m)$ becomes large $\hat{\beta}_{0,n=m}, \hat{\beta}_{1,n=m}$ converge to the true parameters, β_0, β_1 .

$\hat{\beta}_0, \hat{\beta}_1$ are consistent

- We know that:

$$\hat{\beta}_1 = \beta_1 + \frac{S_{Xu}}{S_{XX}} = \beta_1 + \frac{S_{Xu}/N}{S_{XX}/N}$$

- As $N \rightarrow \infty$,

$$S_{Xu} \rightarrow \text{Cov}(X, u)$$

and by the Law of large numbers $S_{Xu}/N \rightarrow 0$

- As $N \rightarrow \infty$,

$$S_{XX} \rightarrow \text{Var}(X) = \sigma^2 X$$

- Therefore, $\text{Plim} \hat{\beta} = \beta$

Assumptions needed for efficiency

- Assumptions on the error, u_i .
 - 1 Assumption of *homoskedasticity*: $u_i \sim$ i.i.d in conditional variance σ^2

$$V(u_i|X_{1,i}) = E(u_i^2|X_{1,i}) = \sigma^2 \quad \forall i$$

- 2 Assumption of serial independence.

$$\text{Cov}E(u_i, u_j|X_{1,i}) = E(u_i u_j|X_{1,i}) = 0 \quad i \neq j$$

Precision of estimators and model

Step 1: How precisely are the estimators observed?

- The “precision of estimators” is captured by the estimator’s variance.

$$\begin{aligned}\text{var}(\hat{\beta}_1) &= \text{var}\left[\beta_1 + \frac{S_{Xu}}{S_{XX}}\right] \\ &= 0 + \frac{1}{[S_{XX}]^2} \text{var}(S_{Xu})\end{aligned}$$

$$\begin{aligned}\text{But } \text{var}(S_{Xu}) &= \text{var}\left[\sum (X_{1,i} - \bar{X})u_i\right] \\ &= \left[\sum \text{var}(X_{1,i} - \bar{X})u_i\right] \text{ by serial independence} \\ &= \sum (X_i - \bar{X})^2 \text{var}(u_i) \\ &= \sigma_u^2 \sum (X_{1,i} - \bar{X})^2 \\ &= \sigma_u^2 S_{XX}\end{aligned}$$

Variance of OLS estimators

- The variance of the estimators are:

$$\text{var}(\hat{\beta}_1) = \frac{\sigma_u^2}{S_{XX}} \quad (1)$$

$$\text{var}(\hat{\beta}_0) = \frac{\sum X_i^2 \cdot \sigma_u^2}{NS_{XX}} \quad (2)$$

$$\text{cov}(\hat{\beta}_0, \hat{\beta}_1) = -\frac{\bar{X}_1 \sigma_u^2}{S_{XX}} \quad (3)$$

Where $S_{XX} = \sum (X_{1,i} - \bar{X}_1)^2$

- The higher the S_{XX} (more variation in X) and larger the sample size, N , the lower is the *se* of the estimated parameters.

With larger samples and higher variability in X, we estimate β more precisely.

- The above are the “true” or population variances, which is unknown because σ_u^2 is unknown.
- We estimate σ_u^2 as:

$$\begin{aligned}\hat{Y}_i &= \hat{\beta}_0 + \hat{\beta}_1 X_{1,i} \\ \Rightarrow \hat{u}_i &= Y_i - \hat{Y}_i \\ \Rightarrow \hat{u}_i &= Y_i - \hat{\beta}_0 - \hat{\beta}_1 X_{1,i} \quad \text{estimate errors} \\ \tilde{\sigma}_u^2 &= \frac{\sum \hat{u}_i^2}{N} \quad \text{Law of large numbers} \\ &\Leftarrow \tilde{\sigma}_u^2 \rightarrow \sigma_u^2\end{aligned}$$

- But the above is biased. An unbiased estimator is:

$$\hat{\sigma}_u^2 = \frac{\sum \hat{u}_i^2}{(N-2)}$$

- $(N-2)$, not N , because there are two parameters to estimate: (β_0, β_1) , using which we got \hat{u}_i . $N > 2$ for the σ_u^2 to be positive

Using σ_u^2 to calculate $\text{var}(\beta)$

- \hat{u}_i satisfy $\hat{\sigma} = \sqrt{\hat{\sigma}^2}$ is
 - Standard error of the disturbances, or
 - Standard error of regression
- The estimated variances are

$$\begin{aligned}\hat{V}(\hat{\beta}_1) &= s_{\hat{\beta}_1}^2 = \hat{\sigma}_u^2 / S_{XX} \\ \hat{V}(\hat{\beta}_0) &= s_{\hat{\beta}_0}^2 = \hat{\sigma}_u^2 \sum X_{1,i}^2 / (NS_{XX}) \\ \widehat{\text{Cov}}(\hat{\beta}_0, \hat{\beta}_1) &= s_{(\hat{\beta}_0 \hat{\beta}_1)} = -\bar{X}_1 \hat{\sigma}_u^2 / S_{XX}\end{aligned}$$

- The square root of the estimated variances above, are called the “standard errors” of the regression coefficients.

Goodness of Fit

- Overall Goodness of F_{it} : many straight lines can pass through the observation paris. The OLS fitted line is the “best”.
- Yet it is imprecise: it does not pass through all the points, because of the errors u_i .
- A quantification of how “good” is the fit of the relationship is captured by the R^2 measure.

Goodness of Fit for $Y_i = \beta_0 + \epsilon_i$

- If we knew only Y_i 's then our best predictor would be \bar{Y} . Then error would be $(Y_i - \bar{Y})$.
- If we square and sum all the errors we get

$$\sum (Y_i - \bar{Y})^2 = \text{TSS, Total sum of squared errors}$$

- Sample standard deviation:

$$\hat{\sigma}_Y = \sqrt{\frac{\sum (Y_i - \bar{Y})^2}{N - 1}}$$

Goodness of Fit for $Y_i = \beta_0 + \beta_1 X_{1,i} + u_i$

- If we know $X_{1,i}, \hat{\beta}_0, \hat{\beta}_1$, and the linear relation between Y_i and $X_{1,i}$, we can compute

$$\hat{Y}_i = \hat{\beta}_0 + \hat{\beta}_1 X_{1,i}$$

$$\Rightarrow \hat{u}_i = Y_i - \hat{Y}_i, \text{ Estimated errors}$$

$$\sum \hat{u}_i^2 = \text{ESS, Error sum of squares}$$

$$\hat{\sigma}_u = \sqrt{\frac{\text{ESS}}{(N-2)}}, \text{ Standard deviation, dispersion of errors}$$

$$Y_i = \beta_0 + \epsilon_i \text{ vs } Y_i = \beta_0 + \beta_1 X_{1,i} + u_i$$

- Compare $\hat{\sigma}_u$ to $\hat{\sigma}_\epsilon$.
- Large reduction means good fitted relation. But $\hat{\sigma}_u$ to $\hat{\sigma}_\epsilon$ depend on unit of measurement.

$$\sum (Y_i - \bar{Y})^2 = \sum (\hat{Y}_i - \bar{Y})^2 + \sum (Y_i - \hat{Y}_i)^2$$

$$TSS = RSS + ESS$$

- Dividing both sides by TSS:

$$R^2 = 1 - \frac{ESS}{TSS}$$

- Thus, $Y_i - \bar{Y} = (\hat{Y}_i - \bar{Y}) + (Y_i - \hat{Y}_i)$
The same holds true for sum of square also: $TSS = ESS + RSS$, or $R^2 = 1 - \frac{ESS}{TSS}$
- $R^2 \rightarrow$ “coefficient of multiple determination”.
Jargon: In single variable case the word “multiple” does not apply. R^2 is instead called “coefficient of determination”.

Characteristics of R^2

- Better the fit, the close are the scatter points to the fitted line.
Then, the lower would be $\sum \hat{u}_i^2$, or ESS, and greater would be RSS.
Thus R^2 is a measure of goodness of fit.
- ESS \rightarrow Unexplained variation.
- RSS \rightarrow Explained variation.
- Thus R^2 is the percentage of total variation explained by model.
- Low R^2 means that a lot of variation in Y_i is unexplained by model.

Features of R^2

- It is obvious that $0 \leq R^2 \leq 1$

$$\begin{aligned} \text{We know that } TSS &= RSS + ESS \\ \frac{TSS}{TSS} &= \frac{RSS}{TSS} + \frac{ESS}{TSS} \end{aligned}$$

$$1 = R^2 + \frac{ESS}{TSS} \rightarrow 1 - \frac{ESS}{TSS}$$

$$\text{Since } 0 \leq \frac{ESS}{TSS} \leq 1 \rightarrow 0 \leq R^2 \leq 1$$

- How to decide if R^2 is high or low?
 \Rightarrow No unique answer

- Show that $E(\hat{Y}_i) = \bar{Y}$.

The OLS model

- Under the assumptions of:

- 1 $Y = X\beta + u$ (linear in parameters)
- 2 $E(\hat{\beta}) = \beta$ (unbiased)
- 3 $E(u|X) = 0$
- 4 X are fixed for i , $\text{Cov}(X_i, u_i) = 0$
- 5 $u_i \sim iid$, such that $\sigma_i^2 = \sigma^2$ (homoskedasticity)
- 6 $\text{Cov}(u_i, u_j|X_i) = 0$, (serial independence)

$$\beta = (X'X)^{-1}(X'Y)$$

- These parameters are called the *Ordinary Least Squares* or “OLS” parameters.
- Note: no distribution assumption on u_j .

OLS is “BLUE”

- The parameters minimising the SSE ($\sum u_i^2$) are *most* efficient among other linear, unbiased, estimators.
- Jargon: OLS parameters are *BLUE*: Best Linear Unbiased Estimators.
- Key to note here: it's only “best” amongst linear and unbiased estimators.

- $\hat{\beta}_1 = \frac{S_{XY}}{S_{XX}}$

$$\begin{aligned}S_{XY} &= \sum X_i Y_i - \frac{1}{N} \sum X_i \sum Y_i \\&= \sum X_i Y_i - \bar{X} \sum Y_i \\&= \sum (X_i - \bar{X}) Y_i\end{aligned}$$

$$\begin{aligned}\text{Rewrite } \hat{\beta}_1 &= \frac{\sum (X_i - \bar{X}) Y_i}{S_{XX}} = \sum \frac{(X_i - \bar{X})}{S_{XX}} \cdot Y_i \\&= \sum \omega_i Y_i\end{aligned}$$

$$\text{Now, } Y_i = \beta_0 + \beta_1 X_i + u_i$$

$$\text{With independence } \Rightarrow \text{var}(Y) = \text{var}(u_i) = \sigma^2$$

$$\text{Therefore, } \text{var}(\hat{\beta}_1) = \sum \omega_i^2 \text{var}(Y_i) = \sigma^2 \sum \omega_i^2$$

Compare with alternative linear unbiased estimators

- $\tilde{\beta}_1 = \sum a_i Y_i$

$$E(\tilde{\beta}_1) = \sum a_i E(Y_i)$$

$$E(\tilde{\beta}_1) = \sum a_i [\beta_0 + \beta_1 X_i]$$

$$\tilde{\beta}_1 = \sum a_i Y_i$$

$$\text{Set } a_i = \omega_i + d_i$$

$$\text{Then } \tilde{\beta}_1 = \sum (\omega_i + d_i) Y_i$$

$$\tilde{\beta} = \sum \omega_i Y_i + \sum d_i Y_i = \hat{\beta}_1 + \sum d_i Y_i$$

$$E(\tilde{\beta}_1) = \beta_1 + \sum d_i E(Y_i)$$

$$= \beta_1 + \sum d_i [\beta_0 + \beta_1 X_i]$$

$$E(\tilde{\beta}_1) = \beta_1 + \beta_0 \sum d_i + \beta_1 \sum d_i X_i$$

- For unbiasedness, we need:

$$\sum d_i = 0, \text{ and } \sum d_i X_i = 0$$

Checking for efficiency of $\tilde{\beta}_1$

- What is the $\text{var}(\tilde{\beta}_1)$

$$\begin{aligned}\text{var}(\tilde{\beta}_1) &= \sum (\omega_i + d_i)^2 \sigma^2 \\ &= \sigma^2 \sum (\omega_i^2 + d_i^2 + 2\omega_i d_i)\end{aligned}$$

$$\text{Therefore, } \text{var}(\tilde{\beta}) = \sigma^2 \sum \omega_{i2} + \sigma^2 \sum d_{i2} + 2\sigma^2 \sum \omega_i d_i$$

- But we know that:

$$\begin{aligned}\sum \omega_i d_i &= \sum \left(\frac{X_i - \bar{X}}{S_{XX}} \right) d_i \\ &= \frac{\sum X_i d_i - \bar{X} \sum d_i}{S_{XX}} = 0\end{aligned}$$

- Which means:

$$\begin{aligned}\text{var}(\tilde{\beta}) &= \sigma^2 \sum \omega_i^2 + \sigma^2 \sum d_i^2 + 2\sigma^2 \sum \omega_i d_i \\ &= \sigma^2 (\sum \omega_i^2 + \sum d_i^2) > \sigma^2 \sum \omega_i^2\end{aligned}$$

- Therefore, $\hat{\beta}_1$ is BLUE.